

Polynomials and (finite) free probability

Adam W. Marcus

Princeton University

`adam.marcus@princeton.edu`

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(with color commentary by Zoidberg)



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Acknowledgements:

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Beyond Kadison-Singer: paving and consequences (AIM)

Hot Topics: Kadison-Singer, Interlacing Polynomials, and Beyond (MSRI)



Outline

1 Introduction

2 Polynomial Convolutions

- The issue with the characteristic map
- The issue with maximum roots

3 Free probability

4 The Intersection

- General ideas
- Connecting polynomials and free probability

5 Application: Restricted Invertibility

Motivation

Recently, I have been interested in self-adjoint linear operators.

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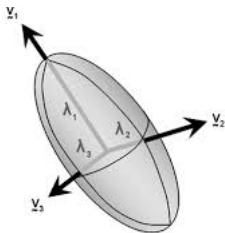
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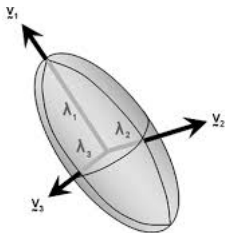


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Algebraically, think: real, square, symmetric, matrices.

Geometrically, think: image of the unit ball is an ellipse.



The λ are called *eigenvalues* and the v their associated *eigenvectors*.

Eigenvalues

Theorem (Spectral Decomposition)

Any $d \times d$ real symmetric matrix A can be decomposed as

$$A = \sum_{i=1}^d \lambda_i v_i v_i^T$$

where the v_i are orthonormal and each pair (λ_i, v_i) is an eigenpair.

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where the v_i are orthonormal and each pair (λ_i, v_i) is an eigenpair.

In particular, if λ_{max} is the largest eigenvalue (in absolute value), then

$$\max_{x: \|x\|=1} \|Ax\| = \lambda_{max}$$

and if λ_{min} is the smallest (in absolute value)

$$\min_{x: \|x\|=1} \|Ax\| = \lambda_{min}$$

Frames

The number of non-zero eigenvalues of A is called the *rank*.

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Example

If $\hat{u}^T \in \{[1, 0], [1, 1]\}$ and $\hat{v}^T \in \{[0, 1], [1, 1]\}$ with independent uniform distributions, then

$$\hat{u}\hat{u}^T + \hat{v}\hat{v}^T \in \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}, \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix}, \begin{pmatrix} 2 & 2 \\ 2 & 2 \end{pmatrix} \right\}$$

each with probability $1/4$.

Known tools

Well-known techniques exist for bounding eigenvalues of random frames.

Theorem (Matrix Chernoff)

Let $\widehat{v}_1, \dots, \widehat{v}_n$ be independent random vectors with $\|\widehat{v}_i\| \leq 1$ and $\sum_i \widehat{v}_i \widehat{v}_i^T = \widehat{V}$. Then

$$\mathbb{P} \left[\lambda_{\max}(\widehat{V}) \leq \theta \right] \geq 1 - d \cdot e^{-nD(\theta \|\lambda_{\max}(\mathbb{E} \widehat{V})\|)}$$

Similar inequalities by Rudelson (1999), Ahlswede–Winter (2002).

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Similar inequalities by Rudelson (1999), Ahlswede–Winter (2002).

All such inequalities have two things in common:

- ① They give results with *high probability*
- ② The bounds depend on the dimension

This will *always* be true — tight concentration (in this respect) depends on the dimension (consider n/d copies of basis vectors).

New method

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Theorem (MSS; 13)

Let $\widehat{V} = \sum_i \widehat{v}_i \widehat{v}_i^T$ be a random frame where all \widehat{v}_i have finite support and are mutually independent. Now let

$$p(x) = \mathbb{E} \left\{ \det \left[xI - \widehat{V} \right] \right\}$$

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be its expected characteristic polynomial. Then

- 1 p has all real roots $r_1 \leq \dots \leq r_m$,
- 2 For all $0 \leq k \leq m$, we have

$$\mathbb{P} \left[\lambda_k(\widehat{V}) \leq r_k \right] > 0 \quad \text{and} \quad \mathbb{P} \left[\lambda_k(\widehat{V}) \geq r_k \right] > 0$$

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Applications have included:

- ① Ramanujan graphs:
 - ▶ Of all degrees, using 2-lifts (MSS; 13)
 - ▶ Of all degrees, using k -lifts (Hall, Puder, Sawin; 14)
 - ▶ Of all degrees and sizes, using matchings (MSS; 15)

- ② Functional Analysis:
 - ▶ Kadison–Singer (and equivalents) (MSS; 13)
 - ▶ Lyapunov theorems (Akemann, Weaver; 14)

- ③ Approximation algorithms:
 - ▶ Asymmetric Traveling Salesman (Anari, Oveis-Gharan; 15)

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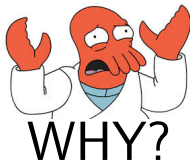
Numerous applications of Kadison–Singer and paving bounds as well.

Big question

Inquiring minds want to know:

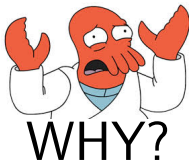
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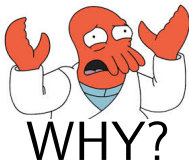
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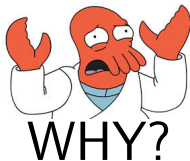


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Why would the expected characteristic polynomial (of all things) provide decent bounds on anything worth bounding?

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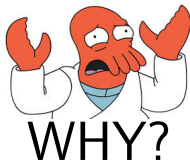
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This talk: introduce a new theory that answers these questions (and more).

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Expected characteristic polynomials

“Prior to the work of [MSS], I think it is safe to say that the conventional wisdom in random matrix theory was that the representation

$$\|A\|_{op} = \maxroot(\det[xI - A])$$

was not particularly useful, due to the highly non-linear nature of both the characteristic polynomial map $A \mapsto \det[xI - A]$ and the maximum root map $p \mapsto \maxroot(p)$.”

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Both are legitimate problems, but for different reasons.

The characteristic map

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So instead consider a rotation invariant operation:

Definition

For $m \times m$ symmetric matrices A and B with characteristic polynomials

$$p(x) = \det [xI - A] \quad \text{and} \quad q(x) = \det [xI - B],$$

the *symmetric additive convolution* of p and q is defined as

$$[p \boxplus_m q](x) = \mathbb{E}_Q \left\{ \det [xI - A - QBQ^T] \right\}$$

where the expectation is taken over orthonormal matrices Q distributed uniformly (via the Haar measure).

Some properties

For degree m polynomials p, q , we have

$$[p \boxplus_m q](x + y) = \sum_{i=0}^m p^{(i)}(x) q^{(m-i)}(y).$$

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For any linear differential operator $R = \sum_i \alpha_i \partial^i$, we have

$$R\{[p \boxplus_m q]\} = [R\{p\} \boxplus_m q] = [p \boxplus_m R\{q\}]$$

So the algebra $(\mathbb{C}_{\leq m}[x], \boxplus_m)$ is isomorphic to $(\mathbb{C}[\partial] \text{ mod } [\partial^{m+1}], \times)$.

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Lemma (Borcea, Brändén)

If p and q have all real roots, then $[p \boxplus_m q]$ has all real roots.

So (when real rooted), we get an easy triangle inequality.

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The second issue is the maximum root — this time the problem lies in stability.

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But then

- ① $\maxroot([p \boxplus_m p]) = 1 + \sqrt{1/m}$
- ② $\maxroot([p \boxplus_m q]) = 1 + \sqrt{1 - 1/m}$



The triangle inequality says it can be at most 2.

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Can we understand the $\alpha\text{max}()$ function?

Brief aside

If you recall the barrier function of Batson, Spielman, Srivastava.

$$\Phi_p(x) = \partial \log p(x) = \frac{p'(x)}{p(x)}$$

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$$\begin{aligned} \alpha \max(p) = x &\iff \maxroot(p - \alpha p') = x \\ &\iff p(x) - \alpha p'(x) = 0 \\ &\iff \frac{p'(x)}{p(x)} = \frac{1}{\alpha} \\ &\iff \Phi_p(x) = \frac{1}{\alpha} \end{aligned}$$

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That is, we are implicitly studying the barrier function.

Some max root results

If p is a degree m , real rooted polynomial, μ_p the average of its roots:

Lemma

$$1 \leq \frac{\partial}{\partial \alpha} \alpha \max(p) \leq 1 + \frac{m-2}{m+2}$$

Proof uses implicit differentiation and Newton inequalities.

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Proof uses concavity of p/p' for $x \geq \maxroot(p)$.

Corollary

$$\mu_p \leq \alpha \max(p) - m\alpha \leq \maxroot(p)$$

Iterate the previous lemma $(m-1)$ times.

Main inequality

Theorem

Let p and q be degree m real rooted polynomials. Then

$$\alpha_{\max}(p \boxplus_m q) \leq \alpha_{\max}(p) + \alpha_{\max}(q) - m\alpha$$

with equality if and only if p or q has a single distinct root.

Proof uses previous lemmas, induction on m , and “pinching”.

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Applying this to $p(x) = x^{m-1}(x-1)$ and $q(x) = x(x-1)^{m-1}$ gives

	$\max\text{root}(\cdot)$	best α in Theorem
$[p \boxplus_m p]$	$1 + 1/\sqrt{m}$	$\approx 1 + 2/\sqrt{m}$
$[p \boxplus_m q]$	$1 + \sqrt{1 - 1/m}$	2

Quick Review

We want to be able to work with expected characteristic polynomials, and had three concerns:

- 1 the real rootedness
- 2 the behavior of the map $A \mapsto \det [xI - A]$
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We addressed the third by using a smooth version of the maximum root function.

On the other hand, we have more explaining to do:



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Definition

A *von Neumann algebra* M on a Hilbert space H is a unital subalgebra of the space $B(H)$ of bounded operators so that

- 1 $T \in M \rightarrow T^* \in M$
- 2 $T_i \in M, \langle T_i u, v \rangle \rightarrow \langle Tu, v \rangle$ for all u, v implies $T \in M$ (closed on weak operator topology).

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We will designate a linear functional $\tau : M \rightarrow \mathbb{C}$ that is

- 1 continuous in the weak operator topology
- 2 unital: $\tau(\mathbb{1}) = 1$
- 3 positive: $\tau(T^* T) \geq 0$
- 4 tracial: $\tau(ST) = \tau(TS)$ for all $S, T \in M$.

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Example

- ① $M = L^\infty(X, \mu)$, with $\tau(T) = \int T d\mu (= \mathbb{E}_\mu\{T\})$
- ② $M = M_{n \times n}$ with $\tau(T) = \frac{1}{n} \text{Tr}[T]$

Random variables

Each operator $T \in (M, \tau)$ defines a probability distribution μ_T on \mathbb{C} by

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for each Borel set $U \subseteq \mathbb{C}$ (δ_U is a WOT limit of polynomials, so $\delta_U(T) \in M$).

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We will think of T is (some sort of) noncommutative random variable.

This generalizes the idea of a (classical) random variable.

Examples

Classic random variables:

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For $\tau = \mathbb{E}\{\}$ and X, Y independent classical random variables,

- ① $\tau(X^2 Y^2) = \tau(X^2)\tau(Y^2)$
- ② $\tau(XYXY) = \tau(X^2)\tau(Y^2)$

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- ① $\tau(X^2 Y^2) = \tau(X^2)\tau(Y^2)$
- ② $\tau(XYXY) = \tau(X^2)\tau(Y^2)$

What's the point of being noncommutative!?!

Free Independence

Definition

T and S are called *freely independent* if

$$\tau(p_1(T)q_1(S)p_2(T)q_2(S)\dots p_m(T)q_m(S)) = 0$$

whenever $\tau(p_j(T)) = \tau(q_j(S)) = 0$ for all j .

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For S, T freely independent,

- ① $\tau(T^2S^2) = \tau(T^2)\tau(S^2)$
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Proof:

Let $S_0 = S - \tau(S)\mathbb{1}$ and $T_0 = T - \tau(T)\mathbb{1}$, so $\tau(S_0) = \tau(T_0) = 0$.

By free independence, $\tau(T_0S_0T_0S_0) = 0$, now substitute and use linearity.

Convolutions

Given r.v. $A \sim \mu_A$ and $B \sim \mu_B$, what is distribution of $A + B$?

Ill defined question (regardless of commutativity)!

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Requires knowing the joint distribution!

However, we know two “special” joint distributions:

Definition

Let μ and ρ be probability distributions with $X \sim \mu$ and $Y \sim \rho$. The

- ① *additive convolution* $\mu \oplus \rho$ is the distribution of $X + Y$ in the case that X, Y are independent.
- ② *free additive convolution* $\mu \boxplus \rho$ is the distribution of $X + Y$ in the case that X, Y are freely independent.

Now how can we compute such things?

Computation

To compute the (classical) additive convolution, one uses the *moment generating function*

$$M_{\mu}(t) = \mathbb{E}_{X \sim \mu} \left\{ e^{tX} \right\}$$

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and then reverses

$$M_{\mu \oplus \rho}(t) = e^{K_{\mu \oplus \rho}(t)}.$$

Only computable up to moments!

Free Computation

To compute the free additive convolution, one uses the *Cauchy transform*

$$\mathcal{G}_{\mu_A}(t) = \int \frac{\mu_A(x)}{t-x} dx = \tau((t\mathbb{1} - A)^{-1})$$

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Note $\frac{1}{t} = \mathcal{G}_{\mu_0}^{-1}(t)$.

Free probability

Voiculescu developed an entire theory (constructed all of the spaces, showed everything converges, etc) which he called *free probability*.

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Furthermore, he showed a link between classical and free independence.

Theorem

Let $\{A_n\}$ and $\{B_n\}$ be sequences of $n \times n$ random matrices where each entry in each matrix is drawn independently from a standard normal distribution. Then there exist operators \mathcal{A} and \mathcal{B} such that

$$\mu_{A_n} \rightarrow \mu_{\mathcal{A}} \quad \text{and} \quad \mu_{B_n} \rightarrow \mu_{\mathcal{B}} \quad \text{and} \quad \mu_{A_n+B_n} \rightarrow \mu_{\mathcal{A}} \boxplus \mu_{\mathcal{B}}$$

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The sequences $\{A_n\}$ and $\{B_n\}$ are called *asymptotically free*.

Many examples of random matrices now known to be asymptotically free.

Quick Review

In free probability, one thinks of probability distributions μ_A and μ_B living on the spectrum of self adjoint operators A and B .

Then one wants to try to understand μ_{A+B} (for example).

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In particular, functions of freely independent random variables are rotation independent!!

This captures “Dysonian” behavior — independence on entries (often) translates to freeness in the spectrum.

Hence it can then be applied to random matrices, but only asymptotically.

Outline

1 Introduction

2 Polynomial Convolutions

- The issue with the characteristic map
- The issue with maximum roots

3 Free probability

4 The Intersection

- General ideas
- Connecting polynomials and free probability

5 Application: Restricted Invertibility

Legendre transform

Definition

Let f be a function that is convex on an interval $X \subseteq \mathbb{R}$. The *Legendre transform* is

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Recall that the R-transform is achieved by inverting the Cauchy transform.

This allows us to achieve it via a **sup**.

L^p norm

Definition

The L_p norm of a function f on a measure space (X, μ) is

$$\|f\|_{L^p(X)} = \left(\int_X |f|^p d\mu \right)^{1/p}$$

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This will be our method of convergence.

Fuglede–Kadison determinants

For $n \times n$ positive definite matrix A , recall

$$\det [A] = \exp \operatorname{Tr} [\log A].$$

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This idea can be extended to von Neumann algebras:

Definition

Given a von Neumann algebra M and trace function τ , the *Fuglede–Kadison determinant* is defined by

$$\Delta(T) = \exp \tau(\log |T|) = \exp \int \log t \, d\mu_{|T|}$$

where $|T| = (T^*T)^{1/2}$.

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where $|T| = (T^*T)^{1/2}$.

Example

For T positive semidefinite in $M_{n \times n}$, $\Delta(T) = (\det [T])^{1/n}$

U Transform

Let S be a multiset of complex numbers.

Claim: there exists a unique multiset T with $|S| = |T|$ such that

$$\prod_{s_j \in S} (x - s_j) = \frac{1}{|T|} \sum_{t_i \in T} (x - t_i)^m.$$

Called the *U transform*.

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Newton identities: power sums \iff elementary symmetric polynomials

Unique solution by fundamental theorem of algebra.

Finite transforms

Let A be an $m \times m$ real, symmetric matrix with maximum eigenvalue ρ_A .

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Definition

The m -finite K -transform of μ_A

$$\begin{aligned} \mathcal{K}_{\mu_A}^m(s) &= -\frac{\partial}{\partial s} \ln \left\| e^{-xs} \Delta(xI - A) \right\|_{L^m(X)} \\ &= -\frac{1}{m} \frac{\partial}{\partial s} \ln \int_X e^{-mxs} \Delta(xI - A)^m dx \end{aligned}$$

where $X = (\rho_A, \infty)$.

The m -finite R -transform is

$$\mathcal{R}_{\mu_A}^m(s) = \mathcal{K}_{\mu_A}^m(s) - \mathcal{K}_{\mu_0}^m(s)$$

where μ_0 is the constant 0 distribution.

The connection

Theorem

For all noncommutative random variables A with compact support, we have

$$\lim_{m \rightarrow \infty} \mathcal{R}_{\mu_A}^m(s) = \mathcal{R}_{\mu_A}(s)$$

Proof uses Legendre transform and convergence of L_p norm. Works for other measures?

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Theorem

Let A and B be $m \times m$ real symmetric matrices. Then the following are equivalent:

- 1 $\mathcal{R}_{\mu_A}^m(s) + \mathcal{R}_{\mu_B}^m(s) \equiv \mathcal{R}_{\mu_C}^m(s) \pmod{[s^m]}$
- 2 $\det[xI - A] \boxplus_m \det[xI - B] = \det[xI - C]$

Proof uses U transform.

Proof sketch

U transform turns polynomial convolutions into classical probability:

Lemma

If Y and Z are independent random variables, then

$$\mathbb{E}\{(x - Y)^m\} \boxplus_m \mathbb{E}\{(x - Z)^m\} = \mathbb{E}\{(x - Y - Z)^m\}.$$

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So $\mathcal{R}_{\mu_A}^m(s)$ must become (linear function of) classical CGF.

Lemma

If A is an $m \times m$ matrix and Y is uniformly distributed over the U transform of $\lambda(A)$, then

$$\mathcal{R}_{\mu_A}^m(s) \equiv \left(\frac{1}{m} \frac{\partial}{\partial s} \log \mathbb{E} \left\{ e^{mYs} \right\} \right) \pmod{[s^m]}$$

The connection, ctd.

Theorem

Let A, B, C be $m \times m$ real, symmetric matrices such that

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Then for all w ,

$$\mathcal{R}_{\mu_C}(w) \leq \mathcal{R}_{\mu_A \boxplus \mu_B}(w)$$

with equality if and only if A or B is a multiple of the identity.

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Follows from “smoothed” triangle inequality:

$$\mathcal{R}_{\mu_A} \left(\frac{1}{m\alpha} \right) = \alpha \max(p) - m\alpha.$$

when $p(x) = \det[xI - A]$.

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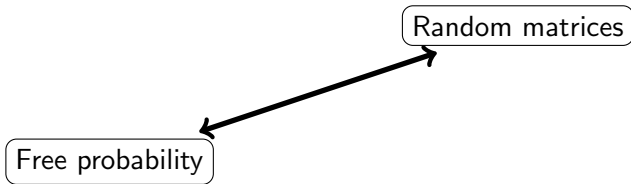
when $p(x) = \det[xI - A]$.

Implies support of finite convolution lies *inside* support of free convolution.

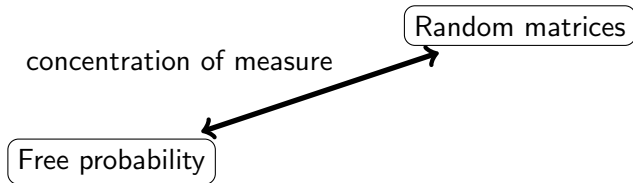
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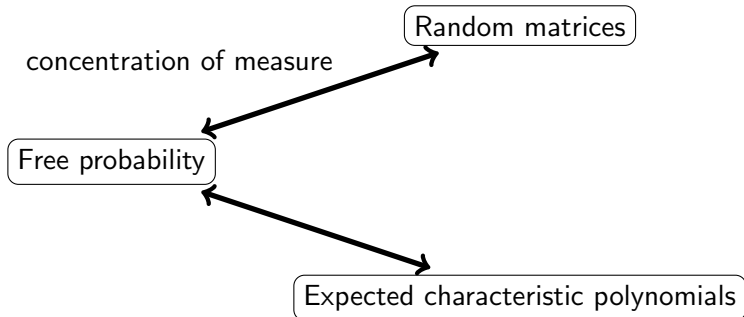
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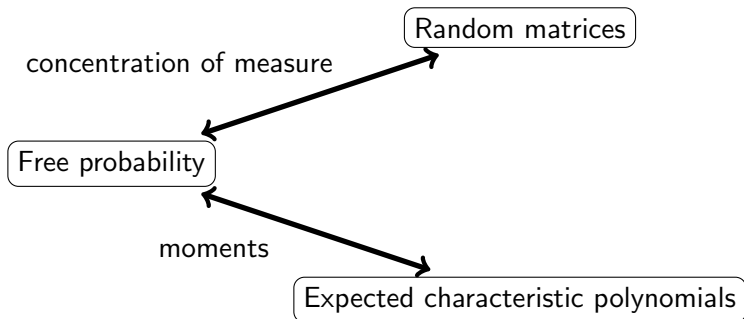
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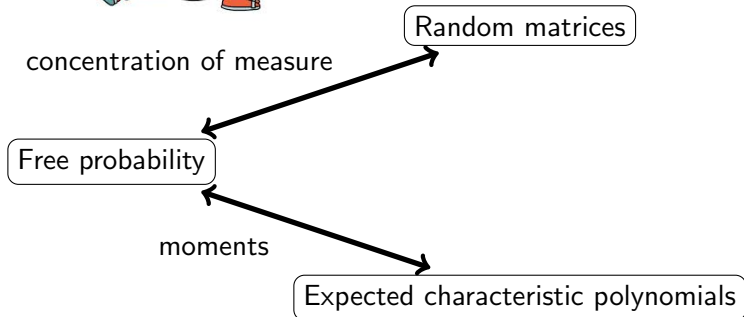
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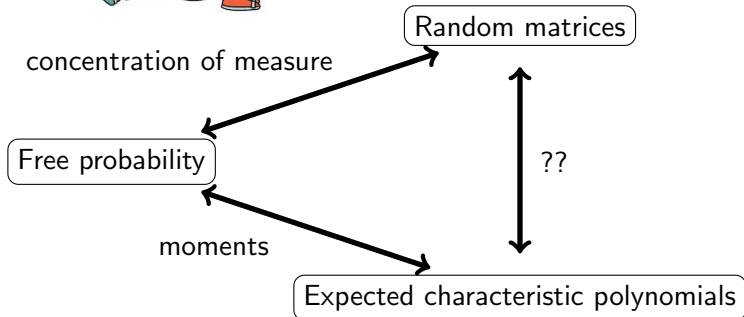


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Similar results for multiplicative convolution.

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Similar results for multiplicative convolution.

Other (known) finite analogues:

- 1 Limit theorems (Central, Poisson)
- 2 Dyson Brownian motion
- 3 Entropy, Fisher information, Cramer–Rao (for one r.v.)

Open directions:

- 1 Bivariate polynomials (second order freeness?)
- 2 Entropy (and friends) for joint distributions

Conjecture

Relation to β -ensembles? Let A, B be $m \times m$ matrices with

$$a_1 = \operatorname{tr} [A] \quad \text{and} \quad a_2 = \operatorname{tr} [A^2]$$

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If A and B are finite freely independent, one gets

$$\operatorname{tr} [(AB)^2] = (*) + \frac{1}{m-1} (a_2 - a_1^2)(b_2 - b_1^2) \quad (**)$$

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And for β -ensembles, one gets (courtesy of Alan Edelman):

$$\mathbb{E}_Q \left\{ \operatorname{tr} \left[(AQ^T BQ)^2 \right] \right\} = (**) - \frac{2m}{(m-1)(m\beta+2)} (a_2 - a_1^2)(b_2 - b_1^2)$$

Giving back

Also potential applications:

- 1 Connes embedding conjecture?

Asks how well vN algebras can be approximated by finite matrices.

Likely requires one of the “open directions.”

Giving back

Also potential applications:

① Connes embedding conjecture?

Asks how well vN algebras can be approximated by finite matrices.

Likely requires one of the “open directions.”

② Random matrix universality?

Universality can often be achieved by studying the asymptotic distribution of roots of certain polynomials.

Which polynomials? Here is a recipe:

Random matrix

→ *free probability*

→ *free convolutions*

→ *finite free convolutions*

→ *polynomial*



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An application

Example: Restricted invertibility (special case)

Theorem

If $v_1, \dots, v_n \in \mathbb{C}^m$ are vectors with

$$\|v_i\|^2 = \frac{m}{n} \quad \text{and} \quad \sum_{i=1}^n v_i v_i^* = I,$$

then for all $k < n$, there exists a set $S \subset [n]$ with $|S| = k$ such that

$$\lambda_k \left(\sum_{i \in S} v_i v_i^* \right) \geq \left(1 - \sqrt{\frac{k}{m}} \right)^2 \left(\frac{m}{n} \right).$$

First proved by Bourgain and Tzafriri (in more generality, worse constants).

Translation

Translate to random matrices:

Given a random $m \times m$ rotation matrix R , and a random set S of size k , what do you expect the eigenvalue distribution of

$$R[S, \cdot]R[S, \cdot]^*$$

to look like?

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to look like?

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Let's see what random matrix theory has to say.

Wishart matrices

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$$d\nu(x) = \frac{1}{2\pi\sigma^2} \frac{\sqrt{(\lambda_+ - x)(x - \lambda_-)}}{\lambda x} \mathbf{1}_{[\lambda_-, \lambda_+]} dx$$

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Called the *Marchenko–Pastur distribution*.

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If this is going to work, it is because the random matrix acts (asymptotically) like a free distribution.

If it acts like a free distribution, it should act like our polynomial convolutions.

To polynomials!

Translate to finite free probability: if

$$p(x) = \det [xI - vv^*] = x^m - \frac{m}{n}x^{m-1}$$

then

$$\underbrace{[p \boxplus_m p \boxplus_m \cdots \boxplus_m p]}_{k \text{ times}} = m!(-n)^{-m} L_m^{k-m}(nx)$$

where $L_m^{(\alpha)}(x)$ is the (very well studied) Laguerre polynomial.

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Same bound can be calculated using $\alpha_{\max}()$ (and picking optimal α).

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Suffices to find distribution on v_1, \dots, v_n so that

- 1 Each choice of a vector is independent
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Hence we want to find a (generic) discrete sum that equals the (generic) integral (for some subset of “generic”).

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Formulas of this type are known as *quadrature rules*.

Quadrature

For special case, choosing uniformly suffices:

Lemma

If A is an $m \times m$ matrix and $\{v_i\}_{i=1}^n \subseteq \mathbb{C}^m$ are vectors with

$$\|v_i\|^2 = \frac{m}{n} \quad \text{and} \quad \sum_i v_i v_i^* = I$$

then

$$\frac{1}{n} \sum_i \det [A + v_i v_i^*] = \mathbb{E}_Q \left\{ \det [A + Q v_1 v_1^* Q^T] \right\}$$

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For full Bourgain-Tzafriri result, need to be more clever.

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Theorem

For all $m \times m$ matrices A and B ,

$$\mathbb{E}_P \left\{ \det \left[A + \hat{P} B \hat{P}^T \right] \right\} = \mathbb{E}_Q \left\{ \det \left[A + Q B Q^T \right] \right\}$$

where

- Q is an orthogonal matrix, distributed uniformly (via Haar measure)
- \hat{P} is a signed permutation matrix, distributed uniformly ($2^n n!$ total)

More connections

Recall the recipe for understanding random matrix distributions:

Random matrix

→ *free probability*

→ *free convolutions*

→ *finite free convolutions*

→ *polynomial*



More connections

Recall the recipe for understanding random matrix distributions:

- Random matrix*
- *free probability*
- *free convolutions*
- *finite free convolutions*
- *polynomial*



The free probability distribution is the *free Poisson distribution*.

The polynomials one studies to learn about Marchenko–Pastur distributions is precisely the collection of Laguerre polynomials we found.

Ramanujan Graphs

Application: existence of Ramanujan graphs of any size and degree.

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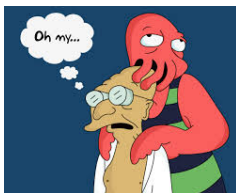
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Details are *far* more complicated:

- 1 generalization of characteristic polynomials to *determinant-like* polynomials.
- 2 special quadrature formula for Laplacian matrices
- 3 new convolution for asymmetric matrices

Thanks

Thank you to the organizers for providing me the opportunity to speak to you today.



And thank you for your attention!